



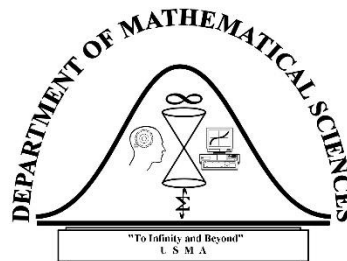
UNITED STATES MILITARY ACADEMY
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Applying the Method of Fundamental Solutions to Algid Soil Freezing Fronts

ARL-USMA Tech Symposium

Samuel Humphries, John Lee, William Nevils,
Matthew Fauerbach, Kameron Grubaugh, Bryce
Wilkins, Dr. Theodore Hromadka

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- Goals:
 - Model a 2-D advancing freezing using the method of fundamental solutions (MFS)
 - Upgrade technology
- Quasi steady-state temperatures along boundary



- Danger posed to roadway embankments
- Interested in:
 - Locating freezing fronts
 - Estimating heat flux values
- Advantages of MFS:
 - Adaptive
 - More convenient
- Advantages of Matlab



- Identify research goals
- Achieve goals
- Conference presentation
- Defend research
- Continue work



- Goal: Approximate a function over a given domain from known data points i.e. fluid flow, heat transfer
- Known points on boundary P_j (collocations)
- Nodes outside problem domain B_j with coefficients c_j
- Use least squares to solve for c_j coefficients to reduce error
- Approximation function is $\sum_{j=1}^n c_j * B_j(P_j)$



- Consider a heat flow problem defined on domain Ω with an exterior boundary Γ
- Objective equation; solve for s (spatial term):

$$L \frac{ds}{dt} = \sum_i Q_{ni}$$

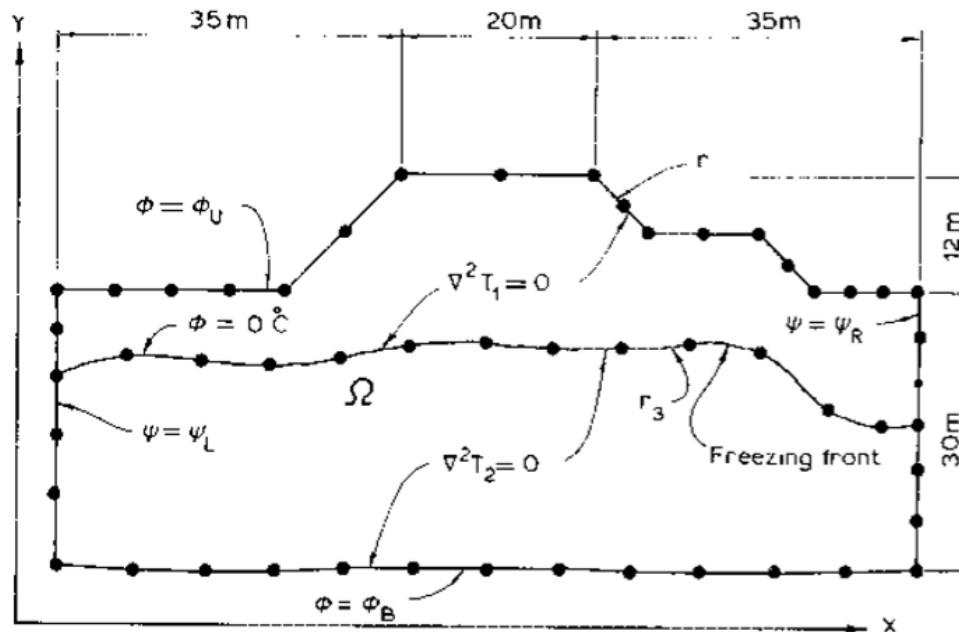


Figure: Roadway Embankment Problem and Nodal Placement



- Heat flux across interior given by:

$$\vec{Q} = -K\vec{\nabla}\varphi$$

where $\varphi(P)$ is the flow potential at any point P.

- For 2-D problems:

$$Q = Q_x + iQ_y = -K \frac{\partial \varphi}{\partial x} - iK \frac{\partial \varphi}{\partial y}$$

- $\varphi(P)$ satisfies the Laplace Equation:

$$\nabla^2 \varphi(P) = 0$$

- Seek to find:

$$u(P) = \frac{\partial \varphi}{\partial x} = \varphi_x(P) \quad \text{and} \quad v(P) = \frac{\partial \varphi}{\partial y} = \varphi_y(P)$$

where $P \in \Omega$.



- Approximation Function:

$$\varphi_n(c, B; P) = \sum_{j=1}^n c_j \log |B_j - P| \quad P \in \Omega$$

- Choose c_j and B_j to minimize least squares functional

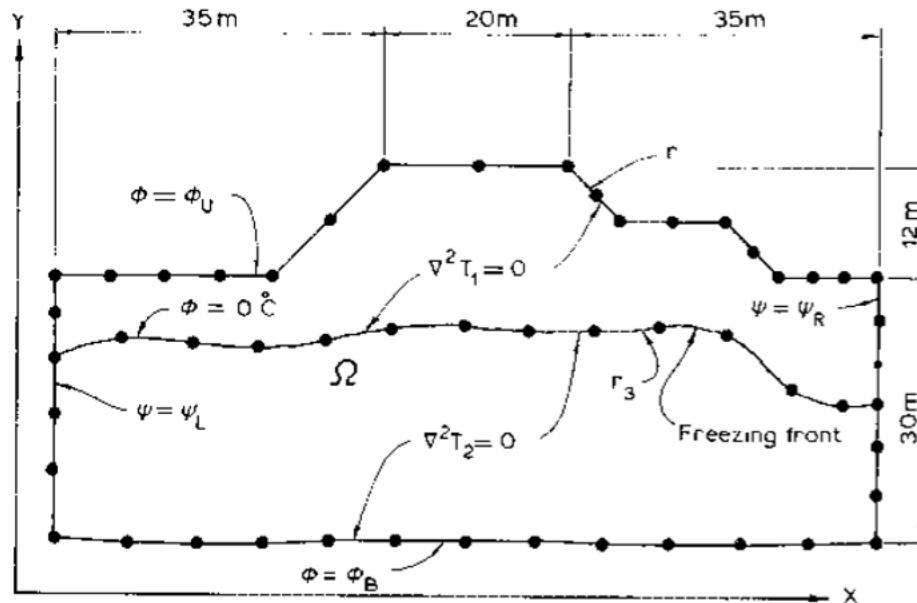


Figure: Roadway Embankment Problem and Nodal Placement



- Velocity Components:

$$u(P) = u_n(c, B; P) = \frac{\partial \varphi_n}{\partial x} = \sum_{j=1}^n c_j \frac{(x - a_j)}{|B_j - P|}$$

$$v(P) = v_n(c, B; P) = \frac{\partial \varphi_n}{\partial y} = \sum_{j=1}^n c_j \frac{(y - b_j)}{|B_j - P|}$$

- Objective Equation; solve for s :

$$L \frac{ds}{dt} = \sum_i Q_{ni} = \sum_i \left(-K \frac{\partial \varphi_{ni}}{\partial x} - iK \frac{\partial \varphi_{ni}}{\partial y} \right) =$$
$$\sum_i \left(-K u_{ni}(P) - iK v_{ni}(P) \right)$$

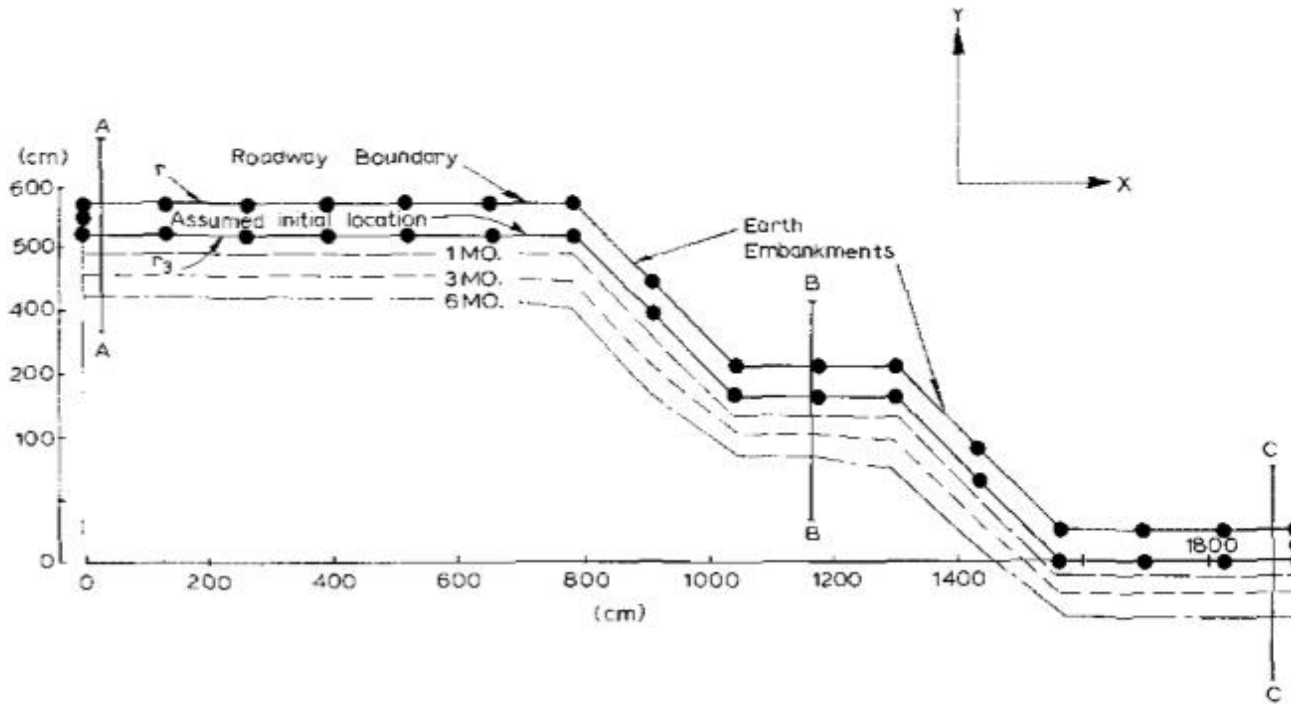
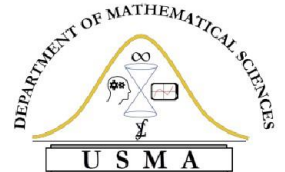


Figure: Estimated Freezing Front Locations



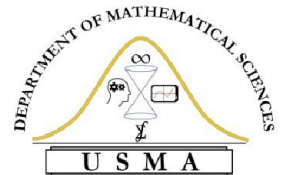
The Conversion

- Upgrade technology to Matlab
 - Improve computational efficiency
 - Include MFS in conjunction with Complex Variable Boundary Element Method (CVBEM)





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QUESTIONS?

